

Physics 239

Lecture 9 - A Closer Look at MRI

- i.) Review of MRI Physics
- ii.) Vertical Field - Full Analysis
- iii.) Resistivity, Viscosity, Partial Ionization
- iv.) Evolution of the MRI

- Vertical Field + Accretion

- 'Mixing Length Theory' of MRI
(Mixing Length Models, Reconnection)

- Fingering and Profile Evolution

- Turbulence - a look

- Disk Dynamo - Comments

→
to be
later

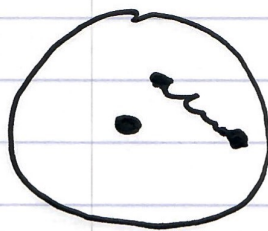
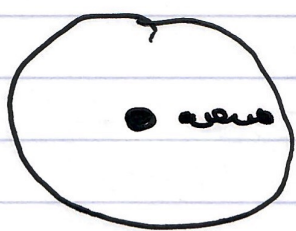
⇒ next:

Fate of the Field: Magnetic Buoyancy,
Parker Instability,

⇒ Hot disk corona.

(i) Review of MRI Physics

- recall



Follows $L-B \propto P$
 $B \propto H$

vertical field:

$$k^2 v_A^2 + \frac{d\Omega^2}{d\ln r} < 0$$

$\rightarrow$ instability criterion

- key points:

$$- \frac{d\Omega^2}{d\ln r} < 0$$

$\rightarrow$ diff. rotation

- weak field:

$$k v_A < \Omega$$

$$(H k > 1)$$

$$\text{not } \Phi < 0 \text{ - is not}$$

$$\frac{2\Omega}{r} \frac{d}{dr} (r^2 \Omega)$$

$\Rightarrow$ stable for strong magnetization

$$- \text{strong} \rightarrow \gamma_{\max} \sim \Omega$$

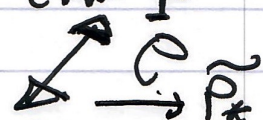
cc.) Vertical Field - Full Analysis

$$\nabla \cdot \mathbf{V} = 0 ; \quad \text{ignore vertical} \quad \left. \begin{array}{l} \text{radial} \\ \text{thermal stratification} \end{array} \right\}$$

$$\tilde{\mathbf{V}} \sim e^{i(\underbrace{k_r r + k_z z}_{\text{variation}} - \omega t)}$$

$$k^2 = k_r^2 + k_z^2$$

$$-i\omega \tilde{V}_r + i k_r \tilde{P} - 2\Omega \tilde{V}_\phi$$


 Rotation

$$+ i \frac{k_r}{4\pi\sigma} (B_z \tilde{B}_z) - i \frac{k_z}{4\pi\sigma} B_z \tilde{B}_r = 0$$

$\frac{B}{4\pi\sigma}$ Magnetic tension - Alfven

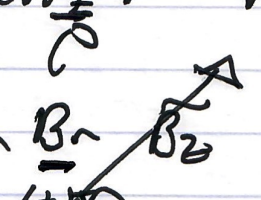
$$-i\omega \tilde{V}_\phi + \tilde{V}_r \frac{k^2}{2\Omega} - i \frac{k_z}{4\pi\sigma} B_z \tilde{B}_\phi = 0$$

$\frac{k^2}{2\Omega} \rightarrow$ Alfvén.

$k^2 \equiv$ epicyclic frequency.

$$k^2 = 2\Omega \frac{d}{dr} (r^2 \Omega)$$

$$-i\omega \tilde{V}_z + i k_z \tilde{P} + i \frac{k_z}{4\pi\sigma} (B_\phi \tilde{B}_\phi + B_r \tilde{B}_r) - i \frac{k_r}{4\pi\sigma} B_r \tilde{B}_z = 0$$


 trivial

and

$$-i\omega \tilde{B}_r - i k_z B_z \tilde{V}_r = 0$$

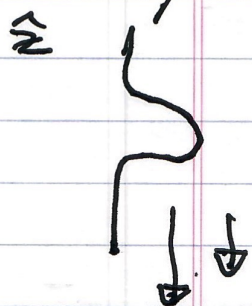
$$-i\omega \tilde{B}_\phi - \left[\tilde{B}_r \frac{r \partial}{\partial r} \right] - i k_z B_z \tilde{V}_\phi = 0$$

$$\mathbf{B} \cdot \nabla \mathbf{V} = \tilde{\mathbf{B}} \cdot \nabla \mathbf{V} + \mathbf{B}_0 \cdot \nabla \tilde{\mathbf{V}}$$

$$\tilde{B}_r \left(\frac{\partial V}{\partial r} - \frac{V}{r} \right) = \tilde{B}_r r \frac{\partial}{\partial r}$$

(see 4a)

key effect



$\Rightarrow$ $\left\{ \begin{array}{l} B_r \text{ tilts } B_z \text{ into} \\ \text{differential rotation} \\ \Rightarrow \text{field stretching} \end{array} \right.$

shear

$$-i\omega \tilde{B}_z - i k_z B_z \tilde{V}_z = 0$$

spring from tilt!

Field
N.B.: - Tilting (magnetic) +
differential rotation
is key to MWT.

- Tilting generates magnetic connection - spring

$$\textcircled{1} \quad \frac{\partial \underline{B}}{\partial t} + \underline{v} \cdot \nabla \underline{B} = \underline{B} \cdot \nabla \underline{v}$$

$$\textcircled{2} \quad (\underline{B} \cdot \nabla \underline{v})_\phi = B_r \frac{\partial v_\phi}{\partial r} + \cancel{\frac{B_\phi}{r} \frac{\partial v_\phi}{\partial z}} + \cancel{B_\phi v_r} + \cancel{B_\phi \frac{\partial v_r}{\partial z}}$$

vert field

$$\approx B_r \frac{\partial v_\phi}{\partial r}$$

$$\textcircled{1} \quad (\underline{v} \cdot \nabla \underline{B})_\phi = \cancel{v_r \frac{\partial B_\phi}{\partial r}} + \cancel{\frac{v_\phi}{r} \frac{\partial B_\phi}{\partial z}} + \cancel{v_z \frac{\partial B_\phi}{\partial z}} + \cancel{\frac{v_\phi}{r} B_r}$$

$$\approx \cancel{v_\phi} \frac{\partial B_r}{\partial r}$$

$$\Rightarrow \frac{\partial \tilde{B}_\phi}{\partial t} = \underline{B} \cdot \nabla \underline{v} - \underline{v} \cdot \nabla \underline{B}$$

$$= \tilde{B}_r \left(\frac{\partial v_\phi}{\partial r} - \frac{v_\phi}{r} \right) = \tilde{B}_r r \frac{\partial \omega}{\partial r}$$

but you know it must be this.

Solid body rotation can't stretch $\tilde{B}_r$ into $\tilde{B}_\phi$. Must be differential.

so, cranking it out:

$$\bar{\omega}^4 \frac{k^2}{k_z^2} - \bar{\omega}^2 \left(4\Omega^2 + \frac{d\Omega^2}{d \ln r} \right) - 4\Omega^2 k_z^2 v_A^2 = 0$$

$$k^2 = k_r^2 + k_z^2$$

$$\bar{\omega}^2 = \omega^2 - (k_z v_A)^2$$

dispersion relation
for axisymmetric
MRI

stability: $-\bar{\omega}^2, \omega^2$ real

$$-\omega^2 > 0$$

so $\omega^2 > 0$ to
 $\omega^2 < 0$ transition
 $\Rightarrow$ instability

so look for $\omega^2 \rightarrow 0$ as $k_z v_A \rightarrow 0$

$$\Rightarrow \frac{d\Omega^2}{d \ln r} < 0 \rightarrow \text{as before}$$

- depends Fennelien hydro

$$\frac{d}{dr} (r^2 \Omega) < 0$$

- azimuthal $\langle B \rangle$ MRI also unstable

- If vertical stratification:

$$N^2 = +g_z \frac{\partial S}{\partial z} \quad S \sim \ln(P_0 - \sigma)$$

$\searrow \quad \searrow$
 Brunt-Vaisala Freq. > 0 for stable

$$\boxed{N^2 + \frac{\partial \Omega^2}{\partial \ln r} > 0.}$$

For stability

$\Rightarrow$ stable stratification vertically works against MRI.

Contrast to:

$$N^2 + \frac{1}{r^3} \frac{\partial (r^4 \Omega^2)}{\partial r} > 0$$

in hydro.

Recall $g \leftrightarrow \Omega^2$ connection
 $\begin{matrix} > 0 & > 0 \\ < 0 & < 0 \end{matrix}$

$\Rightarrow$

$$\omega^2 = \frac{k_r^2 N^2 + k_z^2 \Phi}{k_r^2 + k_z^2}$$

con) Dissipation

- retain ν, η

$$- \gamma = -i\omega$$

$$- \underline{k} = k \hat{z}$$

↓

$$(\gamma + \nu k^2) \tilde{v}_r - 2\Omega \tilde{v}_\phi - \frac{\rho}{\omega^2} \frac{\partial p}{\partial r} = 0$$

$$+ i \frac{k_z B_z}{4\pi\rho} \tilde{B}_r = 0$$

$$(\gamma + \nu k^2) \tilde{v}_\phi + \tilde{v}_r \frac{k^2}{2\Omega} - i \frac{k_z B_z}{4\pi\rho} \tilde{B}_\phi = 0$$

2nd

$$(\gamma + \eta k^2) \tilde{B}_r - i k_z B_z \tilde{v}_r = 0$$

$$(\gamma + \eta k^2) \tilde{B}_\phi - \tilde{B}_r \frac{\partial \Omega}{\partial \ln r} - i k_z B_z \tilde{v}_\phi = 0$$

[here - collisions]

- saturation $\tilde{v}_r, \tilde{v}_\phi$ to render most unstable mode marginal

⇒ Dispersion relation:

$$\left[\gamma^2 + k^2 v_A^2 (\eta + \nu) \gamma k^2 \right]^2 + k^2 \left[\gamma^2 + (k_B v_A)^2 + 2\eta \gamma k^2 \right] - 4 \Omega^2 (k v_A)^2 = 0$$

reduces for $\eta, \nu \rightarrow 0$.

Now, $\gamma' = \gamma_0 - \gamma \rightarrow \gamma$, with η, ν

dissipation rate $\rightarrow \gamma$, about η, ν
 $\rightarrow$ shift in γ

crank:

$$\gamma' \approx \eta k^2 \left[\frac{k^2 (1 + P) [\gamma_0^2 + (k v_A)^2]}{k^2 + 2 [\gamma_0^2 + (k v_A)^2]} \right]$$

for $\gamma' / \gamma_0 < 1$. $\rightarrow$ wk. damping.

$P = \nu / \eta \rightarrow$ Magnetic Prandtl #
 $=$ relative importance.

For Keplerian:

$$P = r/\eta$$

$$\gamma_0^2 = 7/6 \Omega^2$$

$$(kVA)^2 = (5/16) \Omega^2$$

$$\gamma' = \frac{5}{8} \eta k^2 \left(1 + \frac{3}{5} P \right)$$

$\downarrow$
 resistive
 disspn.

$\downarrow$
 r/η

[routine]

~ shift
additive
to #5

~ Exercise:
 η, r effect
on shear Alfvén
wave.

Summary:

$$- P \sim \left(T/10^5 \right)^4 \frac{10^{16}}{\eta}$$

$\downarrow$
 very sensitive to T !

- $P \ll 1 \rightarrow$ need really weak
field to care abt disspn.

$P \gg 1 \rightarrow$ only significant effect
for weak field.

no dissipation does little to MRI

→ Ideal MHD is good!

(*) → What of Partially Ionized { Gases } Fluids?

With neutrals → drag on ions (creep):

$$\underset{\substack{\downarrow \\ \text{force density}}}{\mathbf{f}} = -\gamma \rho_i \rho_n (\mathbf{v}_i - \mathbf{v}_n)$$

2-Fluid analysis ⇒

{ Bloer } Belius

$$(k_z v_A^*)^2 > - \frac{d \rho^2}{d \ln r} \quad \text{for stability}$$

$$v_A^{*2} = \frac{B^2}{4\pi \rho_n} \left[\frac{k^2 + \gamma^2 \rho_i^2}{k^2 + \gamma^2 \rho_i \rho_n} \right]$$

$$\gamma \rightarrow 0 \quad [] \rightarrow 1$$

$$\gamma \rightarrow \infty \quad [] \rightarrow \rho_i / \rho_n \Rightarrow v_A^{*2} = B^2 / 4\pi \rho_n$$

→ strong drag replaces ρ_0 on V_A^2 with ρ_n .

i.e. neutrals constitute 'effective mass' of system, coupled by collisions.

→ in reality;

$$\gamma^2 \rho_i \rho_n \gg K^2$$

$$V_A^2 \rightarrow \frac{B^2}{4\pi\rho_n} \left[1 + \frac{K^2}{\gamma^2 \rho_i^2} \right]$$

so for $\left[\rho_i \gamma \gg K \sim \Omega, \right]$

MRI as usual with $B^2/4\pi\rho_n$.

⇒ * con - neutral collision rate must exceed rotation rate (dynamics) time scale) for magnetic coupling and MRI.

Can relate to:

$$\left| \frac{\dot{M}_i}{\dot{M}_n} \right| = 10^{-13} \left(1 + \frac{m_n}{m_i} \right) \left(\frac{M}{M_\odot} \right)^{1/2} R_{A4}^{-3/2} \left(\frac{D_1}{10^{15}} \right)^{-1}$$

min needed.

→ small

→ important exception → protoplanetary disks
→ accretion.

→ Some Questions:

- why the apparent discontinuous change in stability criteria with B ?

Point: - B enters as $(k \cdot v_A)$

- B will have effect for
 $k \sim \Omega / v_A$

- so long as dissipation not relevant, can always choose high k / small wavelength.

→ scale?

- Key: when does dissipation kick in?

- Angular Momentum Transport?

$$\pi_{r\phi} = r \left[\langle \tilde{v}_r \tilde{v}_\phi \rangle - \langle \frac{\tilde{B}_r \tilde{B}_\phi}{4\pi\omega} \rangle \right]$$

↑
σ(r)v_φ = momentum?

Recall:

$$\partial_t \tilde{B}_\phi = \tilde{B}_r r \frac{\partial \Omega}{\partial r} + B_z \partial_z \tilde{v}_\phi$$

response to tilt generator correlation

⇒

$$\tilde{B}_\phi \sim \int \tilde{B}_r r \frac{\partial \Omega}{\partial r} \sim \gamma \tilde{B}_r r \frac{\partial \Omega}{\partial r}$$

$$- \langle \frac{\tilde{B}_r \tilde{B}_\phi}{4\pi\omega} \rangle \rightarrow - \langle \tilde{B}_r^2 \rangle \gamma_{\text{eff}} r \frac{\partial \Omega}{\partial r} < 0$$

> 0

and magnetic stress $\rightarrow$ outward flux,

(iii) Estimating the Viscosity

- A Mixing Length Theory for MRI

- Why doing all this? $\Rightarrow$ MRI $\rightarrow$ turbulence $\rightarrow$ momentum transport
i.e. get ν !

$\rightarrow$ Caveat Emptor!

- How?

- Numerical Simulation (OO)

$\rightarrow$ assumptions? - boundary conditions

boundary conditions:

- radial $\rightarrow$ inner

- vertical

- Field

$\rightarrow$ interpretation?

Resolution

$\rightarrow \Delta r$

- detailed theory? - tough

- Reduced model $\rightarrow$ mixing length theory.
(guide) $\rightarrow$ intuition

see Shu, 2007

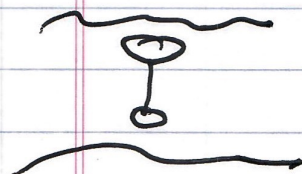
Aside: Mixing Length Theory for Convection

— classic example of mixing length models $\rightarrow$ Convection.

— Recall convection:

cf.:

2020
2186.



$$\rho g = -\frac{d\rho}{dz}$$

$$\rho', \rho' < 0$$

$$\rho e^{-\gamma} \sim \text{const.}$$

blob buoyant if:

super-adiabatic

$$\frac{1}{\gamma} \frac{\gamma}{\rho_i} \frac{d\rho_i}{dz} < \frac{1}{\rho_i} \frac{d\rho_i}{dz} \Rightarrow \frac{d\gamma}{dz} < 0$$

$\Rightarrow$ Schwarzschild condition for convective instability (condition on $\frac{1}{\gamma} \frac{d\gamma}{dz}$)

$\leadsto$ based on idea of a slug or parcel.

$\Rightarrow$ Mixing length theory seeks to model heat flux in terms of a scale length scale or mixing length

N.B.: 'Slug' concept more natural for heat

16.

⇒ A_{in} is to estimate $\left\{ \begin{array}{l} \text{heat flux} \\ \text{thermal diffusivity} \end{array} \right\}$
useful in stellar structure calculations

Seek convective heat flux: $\rightarrow$ transport coefficient (γ)

↑
○
rising parcel

$$\bar{F}_{conv} = \rho (\Delta h) \underline{v} \Rightarrow \rho C_p \langle \tilde{v} \tilde{T} \rangle$$

↓
excess enthalpy (heat)

→ parcel velocity

and parcel exists for length scale

$l_m \rightarrow$ mixing length. ($\sim l_{mix}$)

based on analogy with kinetic theory $\rightarrow$ quantifiable

$$F_{conv} \sim \rho (\Delta h) v_z$$

$\Delta h \sim C_p \Delta T \rightarrow$ excess temperature of rising blob, relative surroundings

$$\Delta T \sim \underset{\substack{\uparrow \\ \text{slug}}}{T'} - \underset{\substack{\uparrow \\ \text{surrounding}}}{T}$$

→ heat of slug.

so $\Delta T \sim l_m (\underbrace{\overline{\partial T} - \overline{\partial T}}_{\substack{\text{difference} \\ \text{in} \\ \text{gradient}}}) \cdot \hat{n}$

$$\hat{n} = -\frac{g}{|g|}$$

For v :

$$\underline{v} \cdot \nabla \underline{v} \sim g \rho$$

$$\rho \underline{v}^2 \sim \Delta \rho |g| \rightarrow f_d \sim \rho A_s v^2$$

l_m dynamic drag



$$\Delta \rho \sim (\partial \rho / \partial T) \Delta T \quad (\text{buoyancy})$$

so $v \sim \left[|g| \frac{(\partial \rho / \partial T) \Delta T l_m}{\rho} \right]^{1/2}$

so

$$F_{\text{conv}} = \rho C_p \left[\frac{\partial \rho}{\partial T} \frac{1}{\rho} g \right]^{1/2} |\overline{\partial T} - \overline{\partial T}|^{3/2} l_m^2$$

heat scaling
of convective flux

$\uparrow$

Typically: $l_m = \alpha H$

$$H^{-1} = \frac{1}{\rho} \frac{\partial \rho}{\partial z}$$

fraction of
pressure scale
height.

and can insert F_{conv} into stellar
 heat transport model. Further
 assumptions/estimates allow statements
 re: profiles / stratification, CF Shu.

Point: - single characteristic length scale

- Link ~~velocity~~ $\left. \begin{array}{l} \text{Temp} \\ \text{perturbation} \end{array} \right\} \ln$

$\Rightarrow$ estimate flux.

$\Rightarrow$ transport model.

- NB: Can have bistable / two-
 scale mixing length models

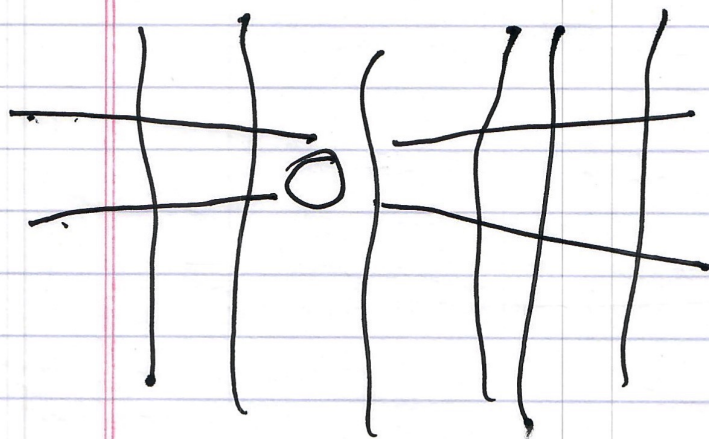
see Balmforth et al. JFM 98

$\Leftrightarrow$ multiple states transport.

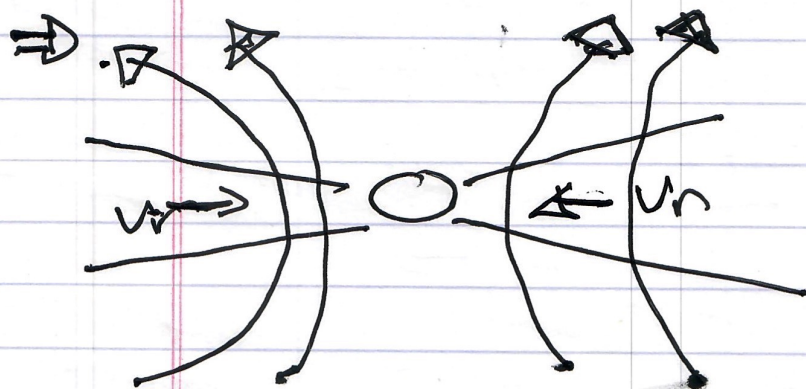
Variant: Model M_T, r_T and calculate conditions for marginality, near marginality.

Now, to Disk:

→ With accretion ($\langle v_r \rangle < 0$), field structure of disk is modified, due Freezing-in law



cf Shu + 2007



accretion flow drags field $\Rightarrow$ bending.

$\langle B_r \rangle \neq 0$ develops.

$$- \oint_{\text{radial field surface}} B_r^+ = \int_0^{\infty} k_0 \left(\frac{r}{r_{\text{cy}}} \right) B_z(r, t) \frac{r}{r_{\text{cy}}^2} dr$$

radial field surface

- For turbulent viscosity, use Maxwell stress, via mixing length approach

$$\text{i.e. } \langle \tilde{B}_r \tilde{B}_\phi \rangle / \mu_0 \rightarrow \mathbb{E}[B^{+2}]$$

$$\text{then link } \tilde{B}_r \leq B_r^+ \\ \tilde{B}_\phi \geq ?$$

= Mixing Model $\rightarrow$ $\delta r \sim$ radial mixing length
Estimate

$$\tilde{V}_r \cdot \nabla B_z \sim \tilde{B}_r r \frac{\partial B_z}{\partial r} \quad (\text{induction})$$

$$\tilde{V}_r \frac{\partial}{\partial r} \tilde{B}_\phi \sim \tilde{B}_r r \frac{\partial \Omega}{\partial r}$$

$$\tilde{B}_\phi \frac{\partial \tilde{V}_r}{\partial r} \sim \tilde{B}_r r \frac{\partial \Omega}{\partial r}$$

$$\frac{\partial \tilde{V}_r}{\partial r} \sim \frac{\tilde{V}_r}{\delta r}$$

$$\boxed{\tilde{V}_r \tilde{B}_\phi \sim \tilde{B}_r r \Omega' \delta r}$$

but $\tilde{V}_r \sim \Omega \delta r$

$$\tilde{B}_\phi \Omega \delta r \sim \tilde{B}_r r \Omega' \delta r$$

$$\boxed{\tilde{B}_\phi \sim \tilde{B}_r \frac{r \Omega'}{\Omega}}$$

ML cancels!
intuitively
plausible

$$\Rightarrow \langle \tilde{B}_r \tilde{B}_\phi \rangle \sim \langle \tilde{B}_r^2 \rangle \frac{r \Omega'}{\Omega}$$

$\langle \rangle$ as avg. $\downarrow$

$$\boxed{\langle \tilde{B}_r \tilde{B}_\phi \rangle = (B^+)^2 \frac{r \Omega'}{\Omega} h}$$

and recall;

$$\Sigma (\partial_t + v_r \partial_r) (v^2 r) = \pm \frac{1}{r} \partial_r \left(r^3 \Sigma v_r r \frac{\partial \Omega}{\partial r} \right)$$

$$\Rightarrow \boxed{v \sim B_r^{+2} h / \Sigma \Omega}$$

$$B_r^+ = B_r^+ \{B_z\}$$

5/5

$$v \sim \frac{B_z^2}{\sum_{\substack{h \\ \neq 0}} \Omega}$$

$$\sim v_A^2 / \Omega$$

→ Alfvén speed
~~sets~~ viscosity

so.

$$\chi = v / c_s h$$

$$= v_A^2 / c_s h \Omega \sim v_A^2 / c_s^2$$

$$\sim 1/\beta$$

$$\boxed{\chi \sim 1/\beta} \rightarrow \text{small}$$

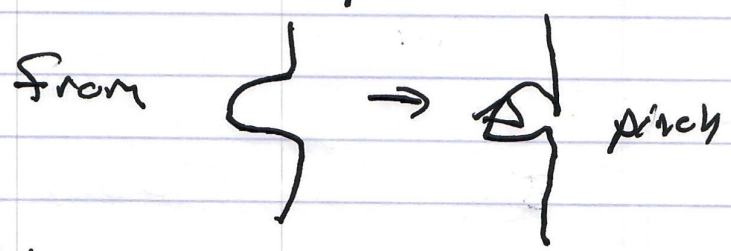
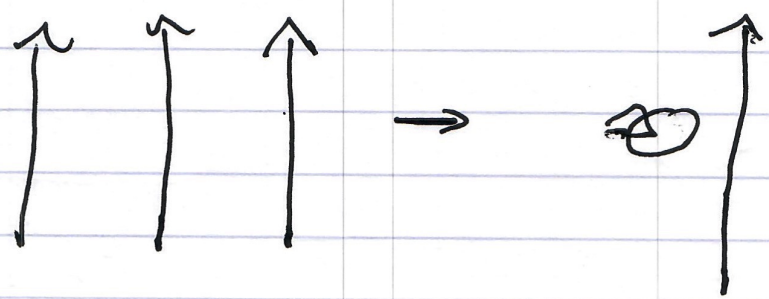
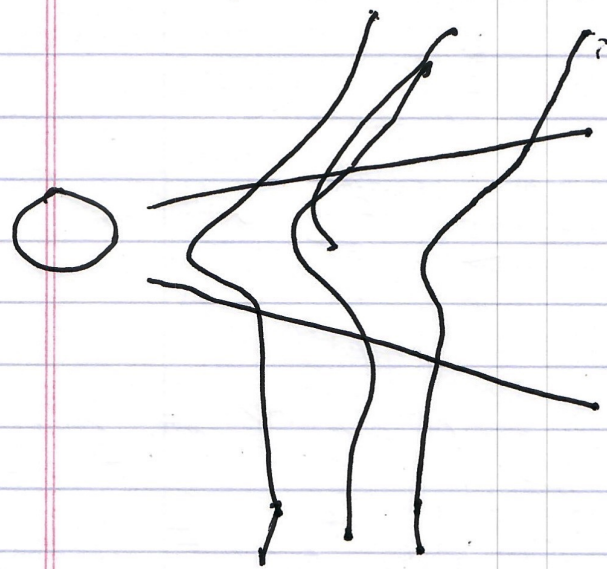
N.B.: - Likely can have $\langle \tilde{B}^2 \rangle > \langle B \rangle^2$

- $\alpha \rightarrow 1$? → some simulations.

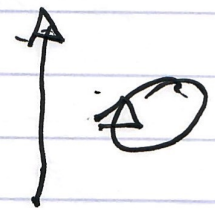
open question

→ What are the Parcels / slugs?

→ Loops $\downarrow$ → of magnetic field, with coupled flux



now; unless twist;

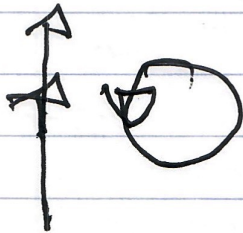


cannot reconnect
↑ ↑ same polarity

$$\Rightarrow \sigma r^2 \sim \text{const} \neq Dt$$

not a walk $\rightarrow$ trapped.

$\rightarrow$ if 3D, twist:



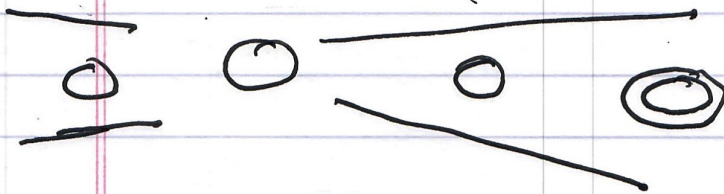
can reconnected.

" parcels are magnetic loops,
random walking due 3D turbulence.

= direction set by secretion flow. }

$\Rightarrow$ Much physics in nonlinear dynamics
of MRI remains!
o.

→ looking ahead: buoyancy



flux tube,
loop.

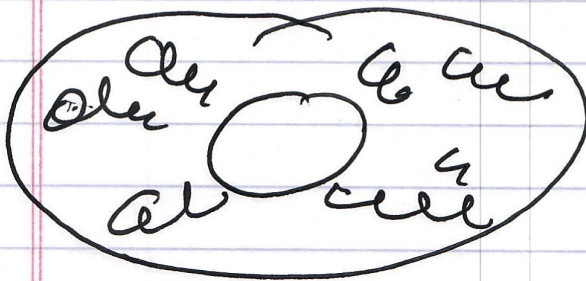
$$P + B^2/8\pi \sim \text{const}$$

high B regions $\rightarrow$ low $P \rightarrow$ low ρ

$$P = P_0 (C/\rho_0)^\gamma$$

Low density $\Rightarrow$ buoyancy

$\rightarrow$ loops
rise to
top of
disk



$\rightarrow$ disk
corona,
etc. etc.